6.895 Randomness and Computation	April 24, 2006
Lecture 18	
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In this lecture we present the relatively recent fundamental result of O. Reingold [3] which establishes that undirected st-connectivity can be decided in deterministic logarithmic space.

Given an undirected graph G, two vertices s and t in G, USTCON(G, s, t) is the problem of deciding whether there exists a path in G connecting s and t. The more difficult, directed graph version of this problem is known to be NL-complete, and thus in L^2 by Savitch's theorem. Prior to the Reingold result, USTCON was known to be in RL [1], and later ([2]) in $\log^{4/3}$. Also, USTCON is a complete problem for the mysterious class SL (symmetric, non-deterministic, log space computations), and therefore USTCON \in L implies SL=L.

We will start by introducing some notation and recalling some results from previous lectures/homeworks.

Definition 1 A (N, D, λ) -graph is an undirected graph on N vertices, of degree D, and with the second largest eigenvalue bounded above by λ .

The relationship between the second eigenvalue and that of vertex expansion is given in the following proposition.

Proposition 2 Let $\lambda < 1$. Then $\exists \varepsilon > 0$ s.t. for any (N, D, λ) -graph $G, \forall S \subset V$, s.t. $|S| < \frac{N}{2}$ we have that $|N(S)| \ge (1 + \varepsilon)|S|$. In this case we say that G is an expander. Note: Elements of S may be in N(S)

Corollary 3 If $\lambda < 1$, then for every connected graph (N, D, λ) , there exists a path of length $O(\log N)$ between any vertices s and t. In particular, G has $O(\log N)$ diameter.

Proof By the vertex expansion property given in Proposition 2, it follows that starting at s and successively following the neighboring sets for $l = O(\log N)$ steps we must have covered > N/2 of the vertices. Repeating the process from vertex t, it must be the case that there is a vertex reached from both s and t in these l steps.

For and expander graph G of constant degree, one can now easily check st-connectivity in log N space as follows:

- Enumerate all D^l paths starting at s of length $l = O(\log N)$.
- If have reached node t then output 'connected', else output 'not connected'.

Notice that the space requirement of the algorithm is $O(\log N \log D)$, which is $O(\log N)$ for constant D. We will reduce the problem of checking st-connectivity in a general graph, to that of checking st- connectivity in an expander graph with constant degree D.

Observation: The results shown in this lecture do not apply to general directed graphs. However, for the special case of directed graphs with constant out-degree equal to the in-degree at each vertex, similar results do hold.

A key fact that will be relevant to the main proof states that the spectral gap $(1 - \lambda(G))$ of any connected, non-bipartite graph G is large enough, namely at least inverse polynomial in |G|, as described next.

Theorem 4 For any connected D-regular and non-bipartite graph G the following holds

$$\lambda(G) \le 1 - \frac{1}{DN^2}.$$

We further add to our toolkit a useful graph.

Theorem 5 There exist a constant D_e and a $(D_e^{16}, D_e, \frac{1}{2})$ -graph.

Also, recall that the graph powering operation is a simple method of increasing the connectivity of a graph.

Proposition 6 (Graph powering) If G is a (N, D, λ) -graph, then the power G^t of G is a (N, D^t, λ^t) -graph.

Observation: Notice that graph powering increases a lot the degree of the new graph. In particular, for a good enough λ we will want $t = O(\log N)$, while we only aim for t = constant. Reingold's proof does use manipulations of graphs using this operation. However, his main ingredient is a new operation (the **zig-zag product**) that will bring down the degree of the graph, while increasing λ by only a small constant factor.

A simple example of a way to lower the degree of a graph is shown in the picture below, where a node is substituted by a cycle.



We next introduce two graph products that have the property that they reduce the degree of a graph while not increasing λ by too much either.

Replacement product:

Given graph an (N, D) graph G and a (D, d) graph H, the replacement product graph G' is obtained from G and H in the following way:

- Each node $v \in G$ is replaced by a copy of H, called H_v . Thus, there are N D nodes in G'.
- Each node $v' \in H_v$ corresponds to an edge from $v \in G$. Therefore, $v' \in H_v$ is adjacent to the *d* nodes in H_v and to a vertex in H_z , where $(v, z) \in E(G)$ and v' corresponds to *z*. Therefore, v' has degree $d + 1 \ll D$.



Zig-zag product:

The zig-zag product G'' of G and H (notation GzH), where G is D-regular and has N nodes and H is d-regular and has D nodes is constructed from the replacement product G' of G and H:

- V(G'') = V(G').
- The edges of G'' are between vertices $x, w \in G'$ that are connected by a path of length three, that starts in $x \in H_v$, takes a step $(x, y) \in E(H_v)$, then follows the edge $(y, z) \in G$, where $z \in H_w$, and finally, takes a step $(z, w) \in E(H_w)$. Therefore, the degree of each vertex is d^2 .

Next we state one of the main tools of the proof, namely the relationship between the second eigenvalues of the graphs G and H to the second eigenvalue of the zig-zag product of G and H.

Theorem 7 ([4]) Let G be a (N, D, λ) -graph, and H be a (D, d, α) -graph. Then GzH is a $(ND, d^2, f(\lambda, \alpha))$ -graph, where $f(\lambda, \alpha) = \frac{1}{2}(1 - \alpha^2)\lambda + \frac{1}{2}\sqrt{(1 - \alpha^2)^2\lambda^2 + 4\alpha^2}$.

In fact, a nicer form of this theorem will be enough for our purposes. The following corollary shows that the spectral gap of the zig-zag product is only larger by a small factor from the spectral gap of G.

Corollary 8 For G, H as above,

$$\frac{1}{2}(1-\alpha^2)(1-\lambda) \le 1-\lambda(GzH).$$

Main Transformation:

Given: G that is D^{16} -regular on N vertices, and H that is D-regular on D^{16} vertices (given by Theorem 5), Let l be the smallest integer s.t. $(1 - \frac{1}{DN^2})^{2^l} < \frac{1}{2}$. Let $G_0 \leftarrow G$ Let $G_i \leftarrow (G_{i-1}zH)^8$ **Output:** $\tau(G, H) = G_l$.

We are now ready for the final construction of the expander graph that we are after. Observation: The number of nodes in G_l is $N(D^{16})^l = \text{poly}(N)$, since $l = O(\log N)$.

Lemma 9 If H is an expander, then G_l is an expander. Equivalently, if $\lambda(H) \leq \frac{1}{2}$ and G is connected and not bipartite, then $\lambda(\tau(G, H)) \leq \frac{1}{2}$.

Proof [Sketch] By Theorem 4 we have that $\lambda(G_0) \leq 1 - \frac{1}{DN^2}$. Notice that it is enough to show inductively that $\lambda(G_i) \leq \max\{\lambda(G_{i-1})^2, \frac{1}{2}\}\}$. This will imply that, for $l = O(\log(N)\log(D))$ we have that $\lambda(G_l) \leq \max\{\lambda(G_0)^{2^l}, \frac{1}{2}\} < \frac{1}{2}$. To prove the induction hypothesis, notice that $\lambda(H) \leq \frac{1}{2}$. By Corollary 8, we have that $\lambda(G_{i-1}zH) < 1 - 1/3$ ($\lambda(G_{i-1})$). Therefore, $\lambda(G_i) < (1 - 1/3)$ ($\lambda(G_{i-1})$)⁸. The conclusion follows then by elementary calculations, by considering the cases $\lambda(G_{i-1}) < 1/2$, and $\lambda(G_{i-1}) \geq 1/2$

We next present an overview of the actual $\log N$ space algorithm solving st-connectivity.

1. Preprocessing stage: make the graph $G^{-}D^{16}$ regular, preserving non-bipartiteness, and the connected components. This can be done by the

replacement product of G with an N-cycle and then adding self-loops. Note that the number of nodes becomes N^2 but this operation is performed only once. Let G_e be the resulting graph.

2. Use the transformation τ described before on the preprocessed graph G_e and H the expander given by Proposition 5.

3. Run the expander algorithm on $\tau(G_e, H)$.

The only tricky part that one needs to verify now is how the walks are performed in log space. The choice of representing graphs G and H as so-called *rotation maps* turns out to be fortunate. This representation implies that each edge is labeled at both its endpoints, which gives a way of tracing a path back from any position by only remembering a constant number of labels.

Definition 10 [3] For a D-regular undirected graph G, the rotation map $Rot_G : [N] \times [D] \rightarrow [N] \times [D]$ is defined as $Rot_G(v, i) = (w, j)$ if the *i*' th edge incident to *v* leads to *w*, and this edge is also the *j*'th edge incident to *w*.

It follows easily that given the rotation map of G one can compute in $\log N$ space the rotation map of G_e . The heart of the problem is showing that the rotation map of $\tau(G_e, H)$ is computable in log space given the rotation maps of G and H. The proof uses an inductive argument and elementary techniques, and we do not attempt it here.

References

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