### Introduction to Algorithms 6.046J/18.401J





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### **Data Structures**

- Role of data structures:
  - Encapsulate data
  - Support certain operations (e.g., INSERT, DELETE, SEARCH)
- Our focus: efficiency of the operations
- Algorithms vs. data structures



# Symbol-table problem

### Symbol table *T* holding *n records*:



#### How should the data structure *T* be organized?

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### **Direct-access table**

**IDEA:** Suppose that the set of keys is  $K \subseteq \{0, 1, ..., m-1\}$ , and keys are distinct. Set up an array T[0 ...m-1]:  $T[k] = \begin{cases} x & \text{if } k \in K \text{ and } key[x] = k, \end{cases}$ 

$$[k] = \begin{bmatrix} NIL & otherwise. \end{bmatrix}$$

Then, operations take  $\Theta(1)$  time.

- **Problem:** The range of keys can be large:
- 64-bit numbers (which represent 18,446,744,073,709,551,616 different keys),
- character strings (even larger!).



## Hash functions



# When a record to be inserted maps to an already occupied slot in T, a *collision* occurs.

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### **Resolving collisions by chaining**

• Records in the same slot are linked into a list.



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# **Analysis of chaining**

We make the assumption of *simple uniform hashing*:

• Each key *k* ∈ *K* of keys is equally likely to be hashed to any slot of table *T*, independent of where other keys are hashed.

Let n be the number of keys in the table, and let m be the number of slots.

Define the *load factor* of *T* to be

 $\alpha = n/m$ 

= average number of keys per slot.



### **Search cost**

Expected time to search for a record with a given key =  $\Theta(1 + \alpha)$ .

apply hash function and access slot

search the list

Expected search time =  $\Theta(1)$  if  $\alpha = O(1)$ , or equivalently, if n = O(m).

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# **Choosing a hash function**

The assumption of simple uniform hashing is hard to guarantee, but several common techniques tend to work well in practice as long as their deficiencies can be avoided.

#### **Desirata:**

- A good hash function should distribute the keys uniformly into the slots of the table.
- Regularity in the key distribution should not affect this uniformity.



# **Division method**

# Assume all keys are integers, and define $h(k) = k \mod m$ .

**Deficiency:** Don't pick an *m* that has a small divisor *d*. A preponderance of keys that are congruent modulo *d* can adversely affect uniformity.

**Extreme deficiency:** If  $m = 2^r$ , then the hash doesn't even depend on all the bits of *k*:

• If  $k = 10110001110100_2$  and r = 6, then  $h(k) = 011010_2$ . h(k)



## **Division method (continued)**

### $h(k) = k \bmod m.$

Pick m to be a prime not too close to a power of 2 or 10 and not otherwise used prominently in the computing environment.

#### Annoyance:

• Sometimes, making the table size a prime is inconvenient.

But, this method is popular, although the next method we'll see is usually superior.



# **Multiplication method**

Assume that all keys are integers,  $m = 2^r$ , and our computer has *w*-bit words. Define

 $h(k) = (A \cdot k \mod 2^{w}) \operatorname{rsh} (w - r),$ 

where rsh is the "bit-wise right-shift" operator and A is an odd integer in the range  $2^{w-1} < A < 2^w$ .

- Don't pick A too close to  $2^{w}$ .
- Multiplication modulo  $2^w$  is fast.
- The rsh operator is fast.



### Multiplication method example

 $h(k) = (A \cdot k \mod 2^w) \operatorname{rsh} (w - r)$ 

Suppose that  $m = 8 = 2^3$  and that our computer has w = 7-bit words:



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## **Dot-product method**

#### **Randomized strategy:**

Let *m* be prime. Decompose key *k* into r + 1 digits, each with value in the set  $\{0, 1, ..., m-1\}$ . That is, let  $k = \langle k_0, k_1, ..., k_{m-1} \rangle$ , where  $0 \le k_i < m$ . Pick  $a = \langle a_0, a_1, ..., a_{m-1} \rangle$  where each  $a_i$  is chosen randomly from  $\{0, 1, ..., m-1\}$ .

Define 
$$h_a(k) = \sum_{i=0}^r a_i k_i \mod m$$
.

• Excellent in practice, but expensive to compute.



# A weakness of hashing "as we saw it"

**Problem:** For any hash function *h*, a set of keys exists that can cause the average access time of a hash table to skyrocket.

• An adversary can pick all keys from  $\{k \in U : h(k) = i\}$  for some slot *i*.

**IDEA:** Choose the hash function at random, independently of the keys.

• Even if an adversary can see your code, he or she cannot find a bad set of keys, since he or she doesn't know exactly which hash function will be chosen.

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## **Universal hashing**

**Definition.** Let *U* be a universe of keys, and let H be a finite collection of hash functions, each mapping *U* to  $\{0, 1, ..., m-1\}$ . We say H is *universal* if for all  $x, y \in U$ , where  $x \neq y$ , we have  $|\{h \in H : h(x) = h(y)\}| = |H|/m$ .

That is, the chance of a collision between x and y is 1/m if we choose hrandomly from H.



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## Universality is good

**Theorem.** Let h be a hash function chosen (uniformly) at random from a universal set H of hash functions. Suppose h is used to hash n arbitrary keys into the m slots of a table T. Then, for a given key x, we have

*E*[#collisions with x] < n/m.



### Proof of theorem

**Proof.** Let  $C_x$  be the random variable denoting the total number of collisions of keys in T with x, and let  $c_{xy} = \begin{cases} 1 & \text{if } h(x) = h(y), \\ 0 & \text{otherwise.} \end{cases}$ 

Note:  $E[c_{xy}] = 1/m$  and  $C_x = \sum_{y \in T - \{x\}} c_{xy}$ .

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 $E[C_x] = E \left| \sum_{y \in T - \{x\}} c_{xy} \right|$  • Take expectation of both sides.

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 $E[C_x] = E \left| \sum_{y \in T - \{x\}} c_{xy} \right|$  • Take expectation of both sides. =  $\sum E[c_{xy}]$  • Linearity of  $v \in T - \{x\}$ 

- expectation.



$$E[C_x] = E\left[\sum_{y \in T - \{x\}} c_{xy}\right]$$
$$= \sum_{y \in T - \{x\}} E[c_{xy}]$$
$$= \sum_{y \in T - \{x\}} \frac{1}{m}$$

- Take expectation of both sides.
- Linearity of expectation.
- $E[c_{xy}] = 1/m.$



$$E[C_x] = E\left[\sum_{y \in T - \{x\}} c_{xy}\right]$$
$$= \sum_{y \in T - \{x\}} E[c_{xy}]$$
$$= \sum_{y \in T - \{x\}} \frac{1}{m}$$
$$= \frac{n-1}{m} \cdot \square$$

- Take expectation of both sides.
- Linearity of expectation.
- $E[c_{xy}] = 1/m$ .

• Algebra.

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# ALGORITHMS

# **Constructing a set of universal hash functions**

Let *m* be prime. Decompose key *k* into r + 1 digits, each with value in the set  $\{0, 1, ..., m-1\}$ . That is, let  $k = \langle k_0, k_1, ..., k_r \rangle$ , where  $0 \le k_i < m$ . **Randomized strategy:** 

Pick  $a = \langle a_0, a_1, ..., a_r \rangle$  where each  $a_i$  is chosen randomly from  $\{0, 1, ..., m-1\}$ .

Define 
$$h_a(k) = \sum_{i=0}^r a_i k_i \mod m$$
. Dot product,  
modulo m  
How big is  $H = \{h_a\}$ ?  $|H| = m^{r+1}$ .  $\leftarrow \frac{\text{REMEMBER}}{\text{THIS!}}$ 

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# Universality of dot-product hash functions

**Theorem.** The set  $H = \{h_a\}$  is universal.

*Proof.* Suppose that

 $x = \langle x_0, x_1, \dots, x_r \rangle$  and

 $y = \langle y_0, y_1, ..., y_r \rangle$  are distinct keys. Thus, they differ in at least one digit position, wlog position 0. For how many  $h_a \in H$  do *x* and *y* collide?

$$h_a(x) = h_a(b) \Leftrightarrow \sum_{i=0}^r a_i x_i \equiv \sum_{i=0}^r a_i y_i \pmod{m}$$

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Equivalently, we have

$$\sum_{i=0}^{r} a_i (x_i - y_i) \equiv 0 \pmod{m}$$

or

$$a_0(x_0 - y_0) + \sum_{i=1}^r a_i(x_i - y_i) \equiv 0 \pmod{m},$$
  
which implies that  
$$a_0(x_0 - y_0) \equiv -\sum_{i=1}^r a_i(x_i - y_i) \pmod{m}.$$

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### Fact from number theory

**Theorem.** Let *m* be prime. For any  $z \in Z_m$  such that  $z \neq 0$ , there exists a unique  $z^{-1} \in Z_m$  such that

 $z \cdot z^{-1} \equiv 1 \pmod{m}.$ 

**Example:** m = 7.

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### **Back to the proof**

We have

$$a_0(x_0 - y_0) \equiv -\sum_{i=1}^r a_i(x_i - y_i) \pmod{m},$$

and since  $x_0 \neq y_0$ , an inverse  $(x_0 - y_0)^{-1}$  must exist, which implies that

$$a_0 \equiv \left(-\sum_{i=1}^r a_i (x_i - y_i)\right) \cdot (x_0 - y_0)^{-1} \pmod{m}.$$

Thus, for any choices of  $a_1, a_2, ..., a_r$ , exactly one choice of  $a_0$  causes x and y to collide.

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# **Proof (completed)**

- *Q*. How many  $h_a$ 's cause x and y to collide?
- **A.** There are *m* choices for each of  $a_1, a_2, ..., a_r$ , but once these are chosen, exactly one choice for  $a_0$  causes *x* and *y* to collide, namely

$$a_0 = \left( \left( -\sum_{i=1}^r a_i (x_i - y_i) \right) \cdot (x_0 - y_0)^{-1} \right) \mod m.$$

Thus, the number of  $h_a$ 's that cause x and y to collide is  $m^r \cdot 1 = m^r = |\mathbf{H}|/m$ .



# **Perfect hashing**

Given a set of *n* keys, construct a static hash table of size m = O(n) such that SEARCH takes  $\Theta(1)$  time in the *worst case*.

**IDEA:** Two-level scheme with universal hashing at both levels. *No collisions at level 2!* 



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## **Collisions at level 2**

**Theorem.** Let H be a class of universal hash functions for a table of size  $m = n^2$ . Then, if we use a random  $h \in H$  to hash *n* keys into the table, the expected number of collisions is at most 1/2. *Proof.* By the definition of universality, the probability that 2 given keys in the table collide under h is  $1/m = 1/n^2$ . Since there are  $\binom{n}{2}$  pairs of keys that can possibly collide, the expected number of collisions is

$$\binom{n}{2} \cdot \frac{1}{n^2} = \frac{n(n-1)}{2} \cdot \frac{1}{n^2} < \frac{1}{2} \cdot \square$$

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# No collisions at level 2

**Corollary.** The probability of no collisions is at least 1/2.

*Proof. Markov's inequality* says that for any nonnegative random variable *X*, we have

 $\Pr\{X \ge t\} \le E[X]/t.$ 

Applying this inequality with t = 1, we find that the probability of 1 or more collisions is at most 1/2.

Thus, just by testing random hash functions in H, we'll quickly find one that works.

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## **Analysis of storage**

For the level-1 hash table *T*, choose m = n, and let  $n_i$  be random variable for the number of keys that hash to slot *i* in *T*. By using  $n_i^2$  slots for the level-2 hash table  $S_i$ , the expected total storage required for the two-level scheme is therefore

$$E\left[\sum_{i=0}^{m-1}\Theta(n_i^2)\right] = \Theta(n),$$

since the analysis is identical to the analysis from recitation of the expected running time of bucket sort. (For a probability bound, apply Markov.)

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# ALGORITHMS

## **Resolving collisions by open addressing**

No storage is used outside of the hash table itself.

- Insertion systematically probes the table until an empty slot is found.
- The hash function depends on both the key and probe number:

 $h: U \times \{0, 1, ..., m-1\} \rightarrow \{0, 1, ..., m-1\}.$ 

- The probe sequence  $\langle h(k,0), h(k,1), \dots, h(k,m-1) \rangle$ should be a permutation of  $\{0, 1, \dots, m-1\}$ .
- The table may fill up, and deletion is difficult (but not impossible).

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### **Probing strategies**

### Linear probing:

Given an ordinary hash function h'(k), linear probing uses the hash function

 $h(k,i) = (h'(k) + i) \bmod m.$ 

This method, though simple, suffers from *primary clustering*, where long runs of occupied slots build up, increasing the average search time. Moreover, the long runs of occupied slots tend to get longer.



### **Probing strategies**

### **Double hashing**

Given two ordinary hash functions  $h_1(k)$  and  $h_2(k)$ , double hashing uses the hash function

 $h(k,i) = (h_1(k) + i \cdot h_2(k)) \mod m.$ 

This method generally produces excellent results, but  $h_2(k)$  must be relatively prime to m. One way is to make m a power of 2 and design  $h_2(k)$  to produce only odd numbers.



# Analysis of open addressing

We make the assumption of *uniform hashing*:

• Each key is equally likely to have any one of the *m*! permutations as its probe sequence.

**Theorem.** Given an open-addressed hash table with load factor  $\alpha = n/m < 1$ , the expected number of probes in an unsuccessful search is at most  $1/(1-\alpha)$ .



## **Proof of the theorem**

### Proof.

- At least one probe is always necessary.
- With probability *n/m*, the first probe hits an occupied slot, and a second probe is necessary.
- With probability (n-1)/(m-1), the second probe hits an occupied slot, and a third probe is necessary.
- With probability (n-2)/(m-2), the third probe hits an occupied slot, etc.

Observe that 
$$\frac{n-i}{m-i} < \frac{n}{m} = \alpha$$
 for  $i = 1, 2, ..., n$ .

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Therefore, the expected number of probes is

$$\begin{aligned} 1 + \frac{n}{m} \left( 1 + \frac{n-1}{m-1} \left( 1 + \frac{n-2}{m-2} \left( \cdots \left( 1 + \frac{1}{m-n+1} \right) \cdots \right) \right) \right) \\ \leq 1 + \alpha \left( 1 + \alpha \left( 1 + \alpha \left( \cdots \left( 1 + \alpha \right) \cdots \right) \right) \right) \\ \leq 1 + \alpha + \alpha^2 + \alpha^3 + \cdots \end{aligned}$$

$$= \sum_{i=0}^{\infty} \alpha^{i}$$
$$= \frac{1}{1-\alpha} \cdot \square$$

 $\sim \sim$ 

The textbook has a more rigorous proof.

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### **Implications of the theorem**

- If  $\alpha$  is constant, then accessing an openaddressed hash table takes constant time.
- If the table is half full, then the expected number of probes is 1/(1-0.5) = 2.
- If the table is 90% full, then the expected number of probes is 1/(1-0.9) = 10.